

CLAIMS

I claim:

1. A walker and tray combination, comprising:

5 a first pair of spaced-apart legs connected to one another by a first upper connecting bar extending between respective points adjacent an upper end of each of the first pair of legs;

a second pair of spaced-apart legs connected to one another by a second upper connecting bar extending between respective points adjacent an upper end of each of the second pair of legs;

10 at least one strut connecting the first pair of legs to the second pair of legs;

a connector configured to selectively retain the tray in one of a primary position, such that first and second connecting bars support the the tray; and,

15 a secondary position, such that the tray is in a plane generally parallel to the first pair of legs.

2. The walker and tray combination as in claim 1, the connector being positioned on a lower surface of the tray and configured to grip the first upper connecting bar when the tray is in one of the primary position or the secondary position.

3. The walker and tray combination as in claim 2, further comprising:

20 a first lower connecting bar extending between the first pair of legs; and,

a second connector on the lower surface of the tray and positioned to grip the first lower connecting bar when the tray is in the secondary position.

4. The walker and tray combination as in claim 2, further comprising:

a second connector on the lower surface of the tray and positioned to grip the second upper connecting bar when the tray is in the primary position.
5. The walker and tray combination as in claim 1, wherein the connector
5 comprises at least one biasable claw configured to releasably grip the walker.
6. The walker and tray combination as in claim 1, wherein the tray is polymethyl methacralate.
7. The walker and tray combination as in claim 1, further comprising
a first handlebar extending upwardly from an upper end of at least one of the first
10 pair of spaced-apart legs; and,

a second handlebar extending upwardly from an upper end of at least one of the second pair of spaced apart legs.
8. The walker and tray combination as in claim 7, wherein the first and second handlebars cooperate to limit movement of the tray in a direction generally parallel to the
15 first and second upper connecting bars when the tray is in the primary position.
9. The walker and tray combination as in claim 1, wherein the tray cantileverly extends outwardly from the walker when the tray is in the primary position.
10. A method of providing a removable tray to a walker, method comprising the steps of:
20 providing a first pair of spaced-apart legs;

connecting the first pair of spaced apart legs to one another by a first upper connecting bar extending between respective points adjacent an upper end of each of the first pair of legs;

providing a second pair of spaced-apart legs;

5 connecting the second pair of legs to one another by a second upper connecting bar extending between respective points adjacent an upper end of each of the second pair of legs;

connecting the first pair of legs to the second pair of legs by at least one strut;

configuring the tray to be selectively connectable to the walker in one of

10 a primary position, wherein the first and second upper connecting bars support the tray; or,

a secondary position, wherein the tray is secured to the walker in a generally parallel relation with each of the first pair of legs.

11. The method as in claim 10, further comprising the step of

15 providing a lower connecting bar connecting the first pair of legs; and positioning a first connector on a lower surface of the tray;

configuring the first connector to grip the first upper connecting bar when the tray is in any one of the primary position or the secondary position; and,

20 positioning a second connector on a lower surface of the tray; and configuring the second connector to grip first lower connecting bar when the tray is in the secondary position.

12. The method as in claim 10, further including the steps of
securing a first connector to a lower surface of the tray in a location adjacent to a
lateral edge of the tray; and,
configuring the first connector to grip the first connecting bar;
5 securing a second connector to a lower surface of the tray;
positioning the second connector to grip the second connecting bar when the tray is
in the primary position.
13. The method as in claim 10, further comprising the step of
selecting biasable claws to serve as connectors that are configured to grip respective
10 portions of the walker.
14. The method as in Claim 10, further comprising the steps of
positioning a first handlebar to extend upwardly from an upper end of at least
one of the first pair of spaced-apart legs;
positioning a second handlebar to extend upwardly from an upper end of at
15 least one of the second pair of spaced apart legs; and,
cooperatively configuring the respective handlebars and the tray so the
handlebars limit movement in a direction parallel to the first and second upper
connecting bars when the tray is in the primary position.
15. The method as in claim 10, further comprising the step of removing the tray
20 from the walker.
16. The method as in claim 10, further comprising the step of making the tray out
of polymethyl methacralate.

17. A walker and tray combination, comprising:

a first pair of spaced-apart legs connected to one another by

a first upper connecting bar extending between respective points

adjacent an upper end of each of the first pair of legs, and

5 a first lower connecting bar extending between respective points

intermediate opposing ends of each leg of the first pair of legs; and,

a second pair of spaced-apart legs connected to one another by a second upper
connecting bar extending between respective points adjacent an upper end of each of the
second pair of legs;

10 at least one strut connecting the first pair of legs to the second pair of legs

a first connector on a lower surface of the tray and configured to

grip the first upper connecting bar when the tray is in a primary
position such that the first and second connecting bars support the tray, and

grip the first upper connecting bar when the tray is in a secondary
15 position such that the connectors retain the tray in a plane generally parallel
to each of the first pair of legs; and,

a second connector on a lower surface of the tray and configured to grip the first
lower connecting bar when the tray is in the secondary position;

a first handlebar extending upwardly from an upper end of at least one of the first pair
20 of spaced-apart legs; and,

a second handlebar extending upwardly from an upper end of at least one of the
second pair of spaced apart legs; wherein,

the tray is positioned on the first and second connecting bars and beneath the first and second handlebars when in the primary position; and wherein,

the first and second handlebars cooperate to limit movement of the tray in a direction generally parallel to the first and second upper connecting bars.

5 18. The walker and tray combination as in claim 17, further comprising
a third connector positioned on a lower surface of the tray and configured to grip the
second upper connecting bar when the tray is in the primary position.

 19. The walker and tray combination as in claim 17, wherein,
the first lower connecting bar and the second upper connecting bar are
10 equidistant from the first upper connecting bar; and wherein,
the second connector is configured to grip the second upper connecting bar
when the tray is in the primary position.